

Categorical Decision Theory

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Decision theory studies decision-making in situations of risk or uncertainty.

There are two branches: *normative* and *descriptive*.

- ▶ Normative DT: how should an “*ideal rational agent*” make decisions?
- ▶ Descriptive DT: how do *actual human beings* make decisions in reality?

This talk is about normative decision theory.

Question. How should a rational agent make decisions in a risky situation?

Answer. (Bernoulli, 1738) Choose actions that maximize *expected utility*.

Question. But why?

Answer. (von Neumann & Morgenstern, 1948) When choosing between lotteries (with objective, known probabilities), EU-maximization is the *only* procedure that satisfies certain axioms of “rationality” or “consistency”.

Question. What about a situation *without* objective, known probabilities?

Answer. (Savage, 1954) The agent should contrive some “subjective” probability distribution, and maximize EU with respect to this.

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- ▶ There is a set \mathcal{S} of possible “states of nature”.
- ▶ The true state is unknown.
 \mathcal{S} represents all the information that is unknown to the agent.
- ▶ There is a set \mathcal{X} of possible “outcomes” (e.g. consumption bundles).
These are the things the agent ultimately cares about.
- ▶ Each alternative defines a function $\alpha : \mathcal{S} \rightarrow \mathcal{X}$, called an **act**.
- ▶ If the agent chooses the act α , and the true state of nature turns out to be s , then she will obtain the outcome $\alpha(s)$.
- ▶ Let $\mathcal{X}^{\mathcal{S}}$ be the set of all logically possible acts.
- ▶ Let \succsim be a **weak order** (a complete, transitive relation) on $\mathcal{X}^{\mathcal{S}}$.
- ▶ For any acts $\alpha, \beta \in \mathcal{X}^{\mathcal{S}}$, the statement “ $\alpha \succsim \beta$ ” means, “The agent prefers α over β , *ex ante*.”

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Savage's Theorem. Suppose \succsim satisfies six axioms (encoding various criteria of “consistency” or “rationality”). Then there exists:

- ▶ a “cardinal utility” function $u : \mathcal{X} \rightarrow \mathbb{R}$, and
- ▶ a (finitely additive) probability measure μ on \mathcal{S} ,

which provide a **subjective expected utility (SEU) representation** for \succsim .

In other words, given any acts $\alpha, \beta \in \mathcal{X}^{\mathcal{S}}$, we have

$$(\alpha \succsim \beta) \iff \left(\int_{\mathcal{S}} u \circ \alpha \, d\mu \geq \int_{\mathcal{S}} u \circ \beta \, d\mu \right).$$

Heuristically, u describes the agent's *desires* concerning outcomes in \mathcal{X} .

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Let's start with two.

- ▶ Endow state space and outcome space with additional structure (e.g. topology or geometry), and require acts to respect this structure.
- ▶ Analyse decision problems *without* explicitly describing the state space and outcome space.

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We will use the following notational conventions.

If \mathcal{C} is a category, then \mathcal{C}° denotes its set of objects.

For any objects $A, B \in \mathcal{C}^\circ$, $\vec{\mathcal{C}}(A, B)$ is the set of \mathcal{C} -morphisms from A to B .

A functor from \mathcal{C} to another category \mathcal{D} is indicated “ $F : \mathcal{C} \mapsto \mathcal{D}$.”

If $G : \mathcal{C} \mapsto \mathcal{D}$ is another functor, then a natural transformation from F to G is indicated “ $\Phi : F \Rightarrow G$.”

For simplicity, this talk focuses on the category **Set** (sets & functions).

But the theory also applies to concrete categories like **Meas** (measurable spaces & measurable functions), **Top** (topological spaces & continuous maps), and **Diff** (differentiable manifolds & smooth maps), and also to abstract categories.

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Part I

Local SEU representations

Let \mathcal{C} be a category. Let $\mathcal{S}, \mathcal{X} \in \mathcal{C}^\circ$ be two objects.

Interpretation:

- ▶ \mathcal{S} = abstract “state space”;
- ▶ \mathcal{X} = abstract “outcome space”;
- ▶ $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$ = set of abstract “acts”.

Let \succsim be a preference order on $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$.

Goal. Find a “subjective expected utility representation” for \succsim .

Problem. In an abstract category \mathcal{C} , what would this even mean?

- ▶ Objects in \mathcal{C}° do not necessarily have underlying sets.
So we cannot represent beliefs by probability measures.
- ▶ Likewise, elements of $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$ are not necessarily functions.
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A **partially ordered vector space (POVS)** is a (real) vector space \mathcal{V} equipped with a partial order that is compatible with addition and scalar multiplication in the obvious way.

Examples. (a) \mathbb{R} is a POVVS with the obvious linear order.

(b) Let \mathcal{S} be a set. The vector space $\mathbb{R}^{\mathcal{S}}$ of real-valued functions on \mathcal{S} is a POVVS with the pointwise dominance order.

An **order unit** for a POVVS \mathcal{V} is an element $u \in \mathcal{V}$ with $u > 0$, such that for any $v > 0$ there is some $r \in \mathbb{R}_+$ with $ru \geq v$.

A **unitary** partially ordered vector space (**UPOVS**) is a POVVS equipped with an order unit.

Examples. (a) 1 is an order unit for \mathbb{R} , making \mathbb{R} a unitary POVVS.

(b) Let \mathcal{S} be a set. Let $\ell^\infty(\mathcal{S})$ be the POVVS of all *bounded* elements of $\mathbb{R}^{\mathcal{S}}$. This is a UPOVS: the constant function $\mathbf{1}_{\mathcal{S}}$ is an order unit for $\ell^\infty(\mathcal{S})$.

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Let **UPOVS** be the category of all unitary partially ordered vector spaces and all uniferent, order-preserving, linear transformations.

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A **utility frame** on \mathcal{C} is a contravariant functor $L : \mathcal{C}^{\text{op}} \Rightarrow \mathbf{UPOVS}$.

Example. Suppose $\mathcal{C} = \mathbf{Set}$.

For any $\mathcal{S} \in \mathbf{Set}^{\text{op}}$, let $L(\mathcal{S}) := \ell^{\infty}(\mathcal{S})$ with order unit $1_{\mathcal{S}}$.

For any $\mathcal{S}_1, \mathcal{S}_2 \in \mathbf{Set}^{\text{op}}$ and $\phi : \mathcal{S}_1 \rightarrow \mathcal{S}_2$, define $L(\phi) : \ell^{\infty}(\mathcal{S}_2) \rightarrow \ell^{\infty}(\mathcal{S}_1)$ by setting $L(\phi)[v] := v \circ \phi$ for all bounded functions $v : \mathcal{S}_2 \rightarrow \mathbb{R}$.

Then L is a utility frame.

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For any $\mathcal{S} \in \mathbf{Set}^{\text{op}}$, let $L(\mathcal{S}) := \ell^\infty(\mathcal{S})$ with order unit $\mathbf{1}_{\mathcal{S}}$.

For any $\mathcal{S}_1, \mathcal{S}_2 \in \mathbf{Set}^{\text{op}}$ and $\phi : \mathcal{S}_1 \rightarrow \mathcal{S}_2$, define $L(\phi) : \ell^\infty(\mathcal{S}_2) \rightarrow \ell^\infty(\mathcal{S}_1)$ by setting $L(\phi)[v] := v \circ \phi$ for all bounded functions $v : \mathcal{S}_2 \rightarrow \mathbb{R}$.

Then L is a utility frame.

Let \mathcal{C} be a category, and fix a utility frame $L : \mathcal{C}^{\text{op}} \Rightarrow \mathbf{UPOVS}$.

Let $F : \mathbf{UPOVS} \Rightarrow \mathbf{Set}$ be the forgetful functor.

Let $\underline{L} := F \circ L : \mathcal{C}^{\text{op}} \Rightarrow \mathbf{Set}$. (This is a presheaf.)

Let $\mathcal{X} \in \mathcal{C}^{\circ}$. Let $\vec{\mathcal{C}}(\bullet, \mathcal{X}) : \mathcal{C}^{\text{op}} \Rightarrow \mathbf{Set}$ be the contravariant hom functor.

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Let \mathcal{X} be a set. Let $u : \mathcal{X} \rightarrow \mathbb{R}$ be a bounded function.

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Thus, $U_{\mathcal{X}} = (U_{\mathcal{X}}^{\mathcal{C}})_{\mathcal{C} \in \mathbf{Set}^\circ}$ is a utility functional.

Indeed, by an application of the Yoneda Lemma, every utility functional can be seen as a generalization of this example.

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Regard \mathbb{R} as a unitary POVS with order unit 1.

For any $\mathcal{C} \in \mathcal{C}^{\circ}$, a **belief about \mathcal{C}** is a **UPOVS**-morphism $\rho : L(\mathcal{C}) \rightarrow \mathbb{R}$.

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Example. Let $\mathcal{C} = \mathbf{Set}$ and let $L = \ell^{\infty} : \mathbf{Set}^{\text{op}} \Rightarrow \mathbf{UPOVS}$.

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Let \mathcal{S} and \mathcal{X} be objects in \mathcal{C}° . Let \succsim be a weak order on $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$.

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A **local subjective expected utility representation** for \succsim is a pair $(\rho, U_{\mathcal{X}})$ where ρ is a belief about \mathcal{S} and $U_{\mathcal{X}}$ is a utility functional on \mathcal{X} , such that:

$$\text{for all } \alpha, \beta \in \vec{\mathcal{C}}(\mathcal{S}, \mathcal{X}), \quad \alpha \succsim \beta \iff \rho [U_{\mathcal{X}}^{\mathcal{S}}(\alpha)] \geq \rho [U_{\mathcal{X}}^{\mathcal{S}}(\beta)]. \quad (*)$$

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Let $u : \mathcal{X} \rightarrow \mathbb{R}$ be bounded. Let $U_{\mathcal{X}} : \vec{\mathcal{C}}(\bullet, \mathcal{X}) \rightrightarrows \underline{L}$ be the utility functional such that, for any $\alpha \in \vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$, we have $U_{\mathcal{X}}^{\mathcal{S}}(\alpha) = u \circ \alpha$.

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A **local subjective expected utility representation** for \succsim is a pair $(\rho, U_{\mathcal{X}})$, where ρ is a belief about \mathcal{S} and $U_{\mathcal{X}}$ is a utility functional on \mathcal{X} , such that:

$$\text{for all } \alpha, \beta \in \vec{\mathcal{C}}(\mathcal{S}, \mathcal{X}), \quad \alpha \succsim \beta \iff \rho [U_{\mathcal{X}}^{\mathcal{S}}(\alpha)] \geq \rho [U_{\mathcal{X}}^{\mathcal{S}}(\beta)]. \quad (*)$$

Example. Suppose $\mathcal{C} = \mathbf{Set}$ and let $L = \ell^\infty : \mathbf{Set}^{\text{op}} \rightrightarrows \mathbf{UPOVS}$.

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Let $u : \mathcal{X} \rightarrow \mathbb{R}$ be bounded. Let $U_{\mathcal{X}} : \vec{\mathcal{C}}(\bullet, \mathcal{X}) \rightrightarrows \underline{L}$ be the utility functional such that, for any $\alpha \in \vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$, we have $U_{\mathcal{X}}^{\mathcal{S}}(\alpha) = u \circ \alpha$.

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There are three more ways that we want to extend Savage's framework.

- ▶ Obtain a single SEU representation that applies to many different decision problems, with different state spaces and/or outcome spaces.
- ▶ Represent the same decision problem with different levels of "awareness", or access to different information sources.
- ▶ Represent "analogies" between different decision problems, or "internal symmetries" within a decision problem.

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Part II.

Decision environments

and

ex ante preferences

Let \mathcal{C} be a category.

A *decision environment* on \mathcal{C} is an ordered pair $(\mathcal{S}, \mathcal{X})$, where \mathcal{S} and \mathcal{X} are subcategories of \mathcal{C} .

Objects in \mathcal{S}° are “abstract state spaces”. (But they might not actually be spaces.) Let’s call them *state places*.

For any \mathcal{S}_1 and \mathcal{S}_2 in \mathcal{S}° , each ϕ in $\vec{\mathcal{S}}(\mathcal{S}_1, \mathcal{S}_2)$ is a \mathcal{C} -morphism from \mathcal{S}_1 to \mathcal{S}_2 that is “compatible” with the agent’s beliefs about \mathcal{S}_1 and \mathcal{S}_2 .

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For any state place \mathcal{S} in \mathcal{S}° and outcome place \mathcal{X} in \mathcal{X}° , the morphisms in $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$ represent “**abstract acts**”.

Let $(\mathcal{S}, \mathcal{X})$ be a decision environment in a category \mathcal{C} .

For every \mathcal{S} in \mathcal{S}° and \mathcal{X} in \mathcal{X}° , let $\succsim_{\mathcal{X}}^{\mathcal{S}}$ be a preference order on $\vec{\mathcal{C}}(\mathcal{S}, \mathcal{X})$, representing the agent's *ex ante* preferences over acts.

$\underline{\triangleright}^{\text{xa}} := \{\succsim_{\mathcal{X}}^{\mathcal{S}}; \mathcal{S} \in \mathcal{S}^\circ \text{ and } \mathcal{X} \in \mathcal{X}^\circ\}$ is an *ex ante preference structure* if:

- (BP) For all $\mathcal{S}_1, \mathcal{S}_2 \in \mathcal{S}^\circ$, $\phi \in \vec{\mathcal{S}}(\mathcal{S}_1, \mathcal{S}_2)$, $\mathcal{X} \in \mathcal{X}^\circ$, and $\alpha, \beta \in \vec{\mathcal{C}}(\mathcal{S}_2, \mathcal{X})$,
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- (DP) For all $\mathcal{X}_1, \mathcal{X}_2 \in \mathcal{X}^\circ$, $\phi \in \vec{\mathcal{X}}(\mathcal{X}_1, \mathcal{X}_2)$, $\mathcal{S} \in \mathcal{S}^\circ$, and $\alpha, \beta \in \vec{\mathcal{C}}(\mathcal{S}, \mathcal{X}_1)$,
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Let $(\mathcal{S}, \mathcal{X})$ be a decision environment in a category \mathcal{C} .

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Objective 1. Define “subjective expected utility representation” for ex ante preference structures over decision environments in abstract categories.

Objective 2. Find necessary/sufficient conditions for the existence of such SEU representations.

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Part III.

Global SEU representations

Let \mathcal{C} be a category, and let $L : \mathcal{C}^{\text{op}} \Rightarrow \mathbf{UPOVS}$ be a utility frame.

Let \mathcal{S} be a subcategory of \mathcal{C} (e.g. state places in a decision environment).

Let $L|_{\mathcal{S}} : \mathcal{S}^{\text{op}} \Rightarrow \mathbf{UPOVS}$ be the restriction of L to \mathcal{S} .

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Proposition. *Let $L := (\infty : \mathbf{Set}^\circ) \models \text{UPOVS}$.*

Let \mathcal{S} be a subcategory of \mathbf{Set} , and let $\{\rho_S\}_{S \in \mathcal{S}^\circ}$ be a belief system.

For all $S \in \mathcal{S}^\circ$, there is a unique finitely additive probability measure μ_S on the power set of S , such that $\rho_S : \ell^\infty(S) \rightarrow \mathbb{R}$ is defined by

$$\rho_S(v) = \int_S v \, d\mu_S, \quad \text{for all } v \in \ell^\infty(S).$$

Also, for all $\mathcal{S}_1, \mathcal{S}_2 \in \mathcal{S}^\circ$, we have $\phi(\mu_{\mathcal{S}_1}) = \mu_{\mathcal{S}_2}$, for all $\phi \in \vec{\mathcal{S}}(\mathcal{S}_1, \mathcal{S}_2)$.

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The set of all positive affine transformations forms a group \mathbf{Aff} under composition, which we can regard as a single-object category.

Let \mathcal{V} be a unitary POVS with order unit $\mathbf{1}_{\mathcal{V}}$.

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Example. Suppose $\mathcal{C} = \mathbf{Set}$ and $L := \mathbb{R} : \mathbf{Set}^\circ \mapsto \mathbf{UPOVS}$.

For all $\mathcal{X} \in \mathcal{X}^\circ$, let $u_{\mathcal{X}} : \mathcal{X} \rightarrow \mathbb{R}$, and define the utility functional $U_{\mathcal{X}} = (U_{\mathcal{X}}^{\mathcal{C}})_{\mathcal{C} \in \mathcal{C}^\circ} : \vec{\mathcal{C}}(\bullet, \mathcal{X}) \rightrightarrows \underline{L}$ as before.

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Let $(\mathcal{S}, \mathcal{X})$ be a decision environment in a category \mathcal{C} .

Let $\underline{\succ}^{xa}$ be an ex ante preference structure on $(\mathcal{S}, \mathcal{X})$.

A **global subjective expected utility representation** for $\underline{\succ}^{xa}$ consists of:

- ▶ A utility frame $L : \mathcal{C}^{\text{op}} \rightarrow \mathbf{UPOVS}$;
- ▶ A belief system $(\rho_S)_{S \in \mathcal{S}^\circ}$; and
- ▶ A utility system given by $(U_{\mathcal{X}}^{\mathcal{C}})_{\mathcal{X} \in \mathcal{X}^\circ}^{\mathcal{C} \in \mathcal{C}^\circ}$ and $A : \mathcal{X} \rightarrow \mathbf{Aff}$;

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Let $(\mathcal{S}, \mathcal{X})$ be a decision environment in a category \mathcal{C} .

Let $\underline{\triangleright}^{\text{xa}}$ be an ex ante preference structure on $(\mathcal{S}, \mathcal{X})$.

A **global subjective expected utility representation** for $\underline{\triangleright}^{\text{xa}}$ consists of:

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Question. Under what conditions does an ex ante preference structure have a global SEU representation?

Answer. Using an approach inspired by Anscombe & Aumann (1963), we prove a theorem giving necessary & sufficient conditions for an ex ante preference structure to have a global SEU representation.

Furthermore, in the category **Top**, we can ensure that the utility functions are continuous, and beliefs are represented by Borel probability measures.

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Prologue

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- The Savage Framework
- Savage's Theorem
- Desiderata I

Part I. Local SEU representations

- Goal: SEU representations for ex ante preferences
- Partially ordered vector spaces
- Utility frames
- Utility functionals
- Beliefs
- Local SEU representations
- Desiderata II

Part II. Decision environments and ex ante preferences

- Decision environments
- Ex ante preference structures
- Definition

Part III. Global subjective expected utility representations

- Belief systems

Positive Affine Transformations

Utility systems

Global SEU Representation

Sketch of the SEU representation theorem

Thank you